CENTER FOR COMPACT AND EFFICIENT FLUID POWER

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Investigation of Noise Transmission through Pump Casing

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Structural Acoustic Paradigm



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Analysis Overview Pressure Mechanical Acoustical Pump Sound loading Response Radiation Response Structure of surfaces Mechanical Coupling Radiation Generation Perception **Propagation** Transmission Surface Acoustic Port Sound pressure normal pressures camera Intensity velocity field **Far-Field** Bore • Structural **Empirical Spherical** Pressure Sound Power Transfer attenuation Harmonics Pressure **ISO** Loudness Spectrums **Functions** Operational modal Pressure FFT Module sims Near-field holography 1/3 Octave



Experimental Facilities



Characterize the measured sound field in spatial, temporal, and frequency domains.



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Automated Spatial Sampling



Custom robot for automated method of measuring sound intensity at any given number of evenly spaced locations.





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Floor Reflections Removal





Direct path Wall reflected path Floor reflected path Microphone



Final Grid and Path

NUMBER OF CART

Inner arm [deg]

225-point Grid



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Updated Chamber







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Perception



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Example Perception Results







11

Frequency Analysis



Example measurement:

A pump with 9 pistons @ 3000 rpm

Pump Harmonic Frequencies: **450** Hz, **900** Hz, **1350** Hz, **1800** Hz ...

5Max1 SIL Harm 1 (mean: 74.5 dB)

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SIL [dB]



Frequency Analysis

Simplify the frequency analysis

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Octave: upper band frequency is the lower band frequency multiplied by 2

1/3 Octave: upper band frequency is the lower band frequency multiplied by $\sqrt[3]{2}$







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Spherical Harmonics (radiation)

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Measured Pressure Field (1200rpm, Frequency: 0-25kHz)







1.2

1

Acoustic Holography

- Reconstruct the sound field; for every location and any time
- 1. Particle velocity
- 2. Sound pressure
- **Consequentially:**
- 1. Modal vibrational pattern
- 2. Vector intensity field
- 3. Far-field radiation pattern
- 4. Total radiated power

(DeVries , 1994)

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Acoustical Meaning of S.H. Functions





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1.5

Pulsating force



1.5

1.5

1

-0.5 0 0.5 1

-1 -0.5 0 0.5

-1.5

Pulsating moment

17

Wave Equation Decomposition





 $p(r,\theta,\phi,t) = R(r)P(\theta)\Phi(\varphi)e^{-j\omega t}$

Radial Part Solution:

$$R(r) = h_n(kr) \cong \frac{1}{r^n}$$

Directional Part Solution:

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$$P(\theta)\Phi(\varphi)=Y_n^m$$

Spherical Harmonic Functions



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From Theory to Practice



Least Square Fitting Truncate to finite order N, and write as matrix form: $(N+1)^2$ unknowns $\boldsymbol{Y} = \begin{bmatrix} Y_0^0(\theta_1, \phi_1) & Y_1^{-1}(\theta_1, \phi_1) & \dots & Y_N^N(\theta_1, \phi_1) \\ Y_0^0(\theta_2, \phi_2) & Y_1^{-1}(\theta_2, \phi_2) & \dots & Y_N^N(\theta_2, \phi_2) \\ \vdots & \vdots & \ddots & \vdots \\ Y_0^0(\theta_M, \phi_M) & Y_1^{-1}(\theta_M, \phi_M) & \dots & Y_N^N(\theta_M, \phi_M) \end{bmatrix} \boldsymbol{M} \text{ equations}$ m $\boldsymbol{c} = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_{(M+1)^2} \end{bmatrix}, \qquad \boldsymbol{p} = \begin{bmatrix} q_1 \\ q_2 \\ \vdots \\ q_M \end{bmatrix}$ n 2 Yc = p** * * 👙 👙 * ** $c = Y^{-1}p \Leftrightarrow Yc - p = 0$ 3 $c = Y^+ p \iff min(||Yc - p||)$ ********** 4

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Measurement Fitting



0



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0.05

LS Fitting on N = 0

Measured Pressure Field 1200rpm, 1st harmonic (180 Hz)











х



Near-Field Holography In Progress

Pump Surface

Pump Surface



Far-field holography capture's only the propagating pressure waves

> The pressure field also includes **Evanescent waves,** which decay exponentially with distance.

Near-field holography capture's both the propagating and evanescent waves



Near-Field Arm

In Progress

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A near field arm is being manufactured.

An additional arm added to the robot will help improvements measurements:

- Easier / faster
- Repeatable

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27



Propagation





Surface Vibrations Example 1200rpm





Structural Attenuation In Progress

- Consistent spikes in multiple accelerometers yield the structural modes and resonances.
- Relative phase of different pump locations reveals the mode shapes.
- A designer can

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- Design valve plates based on 1. the Structural Attenuation
- Add mass/stiffness to effect the 2.

Structural Attenuation



30





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Operational Modal Analysis



Basic Frequency Response Equation (SDOF) • $H(w) = \frac{X_1(w)}{X_2(w)} = FRF$ Magnitude (g/N) H(w) == FRF $\dot{\omega}_2 \omega_3$ ω Frequency (Hz)

(Avitabile, 2003)



Generation





Fast Pressure Sensors High Pressure Port (1200rpm, 200 bar)





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Conclusion and Future Work



Conclusions

- Maha's sound chamber has been successively remodeled.
- Preliminary measurements have been made to generate realistic data for analysis development.
- A few new analysis techniques have been highlighted

Future Work:

 Continue working on Analysis tools to fully map the oscillatory energy pathways.



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Thank You Any Questions?



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