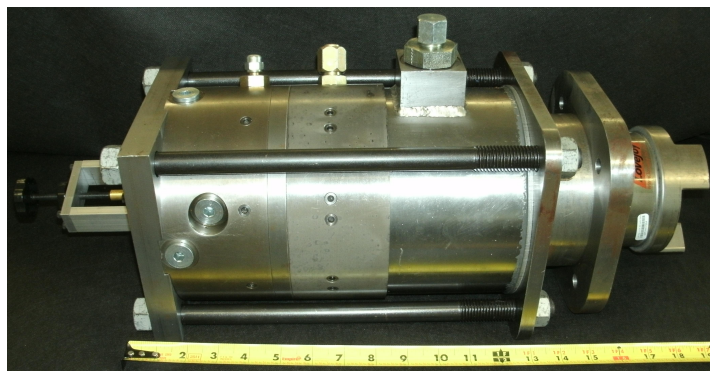


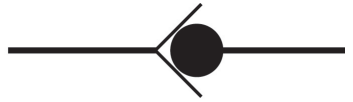


High Efficiency Hydraulic Pump-Motors Employing Partial Stroke Piston Pressurization



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Dr. Thomas Chase
Dr. Perry Li





Hydraulic power - applications



Image taken from: https://www.caseih.com/northamerica/en-us/products-skid-steers/wheeled_skid_steer



Image taken from: <https://www.bobcat.com/loaders/compact-track-loaders/models/t590/photos-videos#lightbox-t590-m2-grapple-hay>





Existing Technology

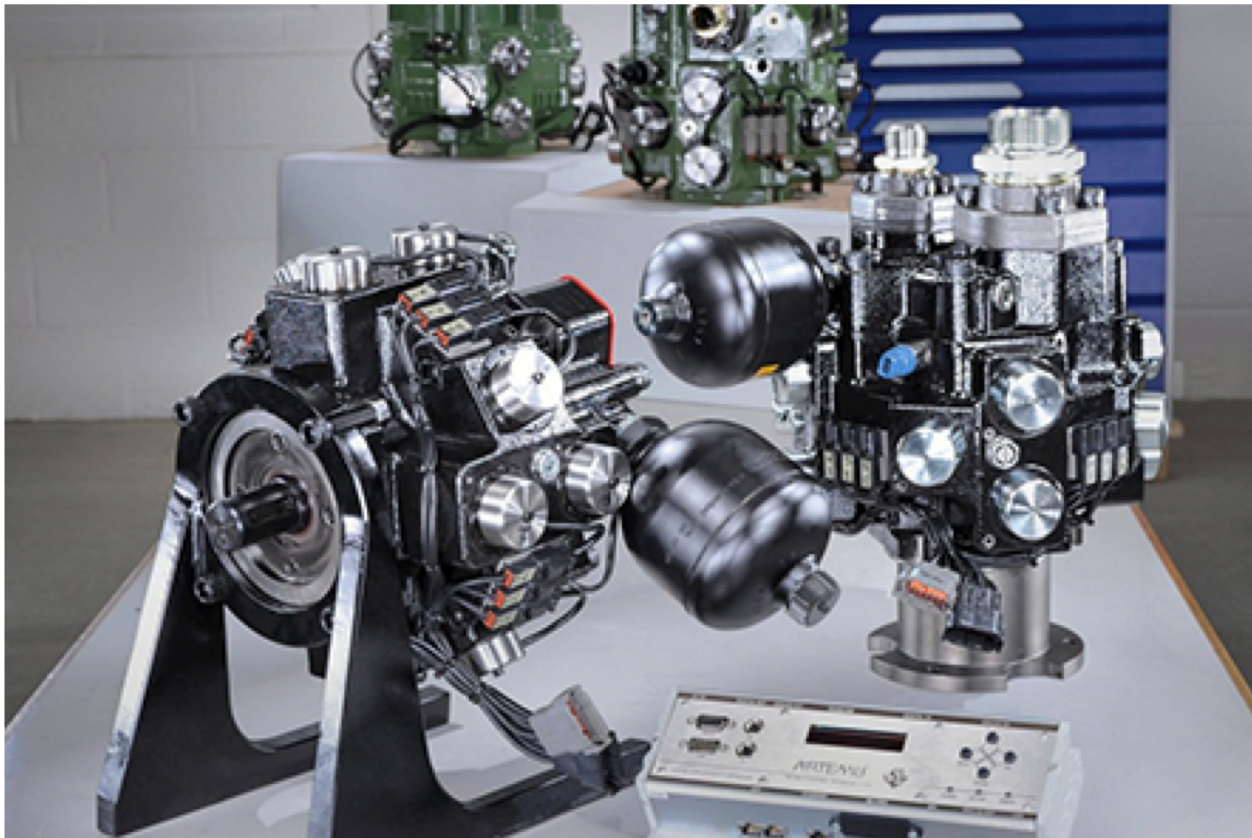
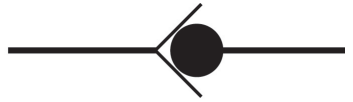


Image taken from: <http://www.artemisip.com/our-products/industrial-hydraulic-pump>

Artemis Digital Displacement

- Two valves per piston
- Electronic sensors and controls
- Expensive



Our approach: Hydro-Mechanical Control

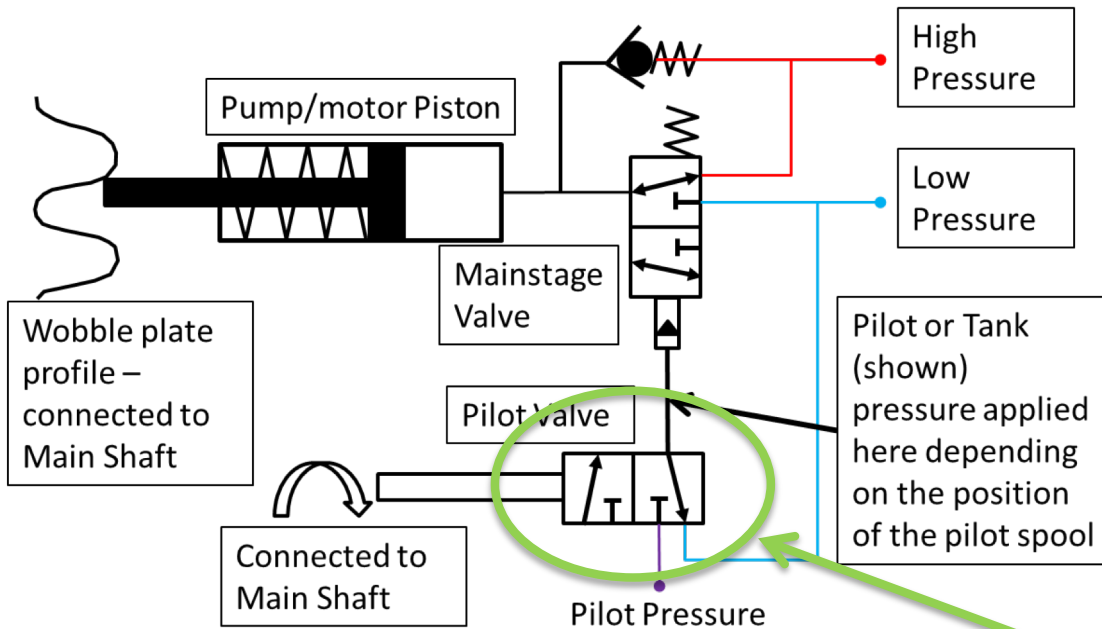
- Most discrete-piston implementations use electromagnetic valves:
 - 2 valves per piston
 - Artemis; others

Advantages of mechanical control – valve timing connected to shaft

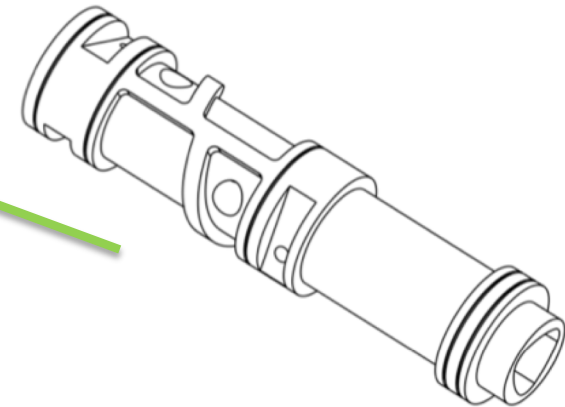
- **Robust:** No solenoids/wires/power electronics to fail on each piston
- **Cost:** No controllers for each piston
- **Simple:** only 1 control input needed
- **Mechanical and hydraulic power:** No need for electrical supply
- **Fast and repeatable timing:** speed scales up with pump speed



Concept

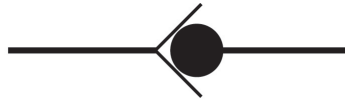


- Two stage
 - 2D Rotary valve pilot stage
 - Spool valve main stage

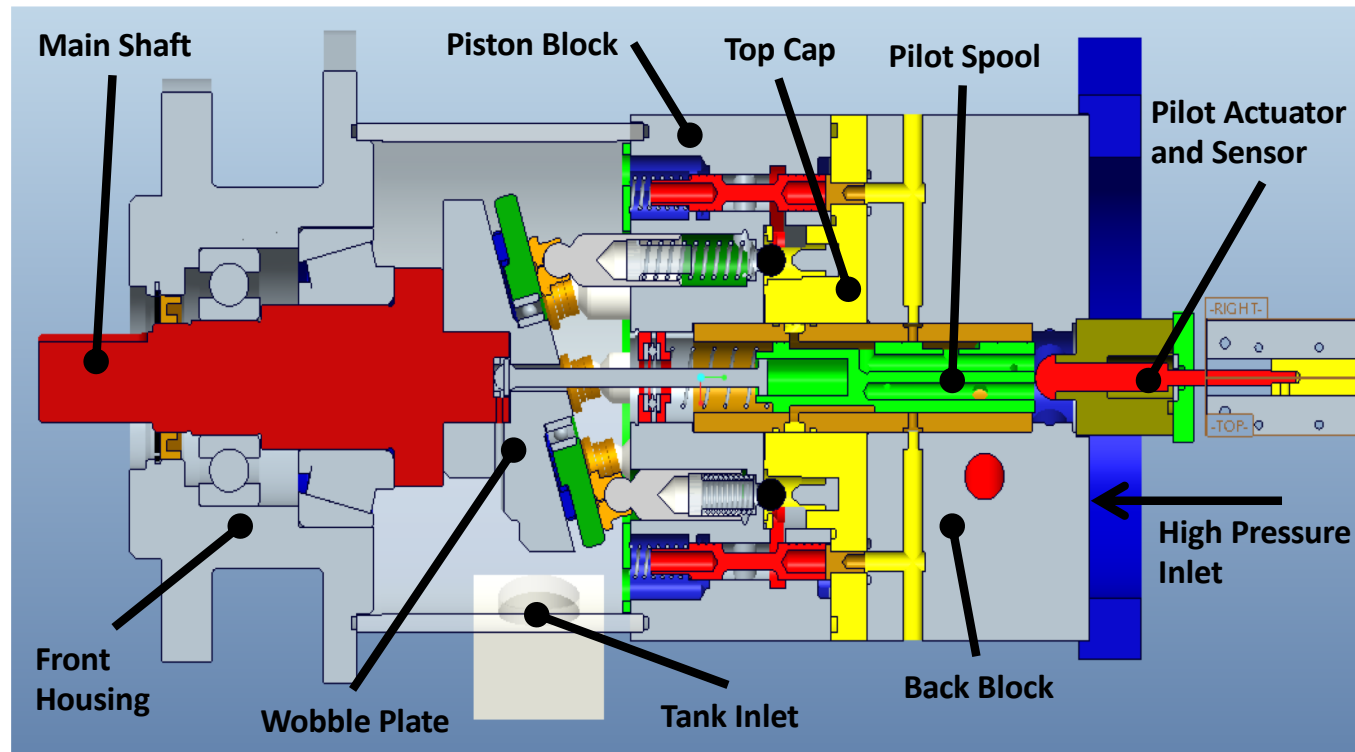


Pilot stage = 2 Degree-of-freedom valve:

- Rotation with shaft
- Translation: adjust displacement



Cutaway CAD model

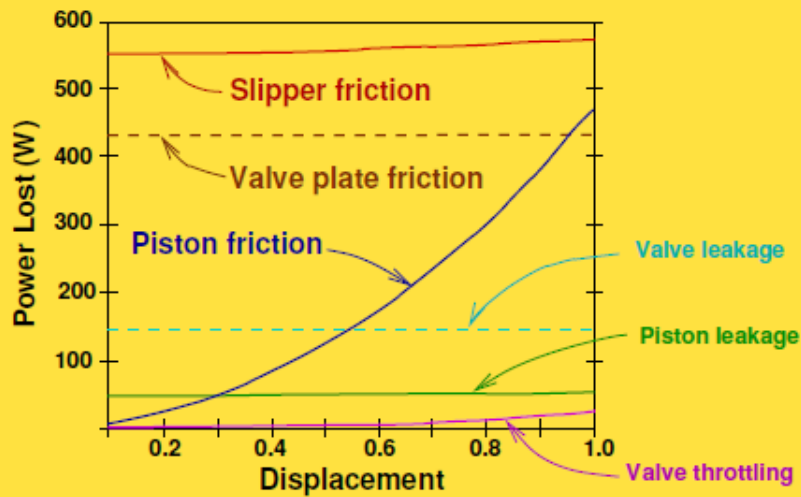




Why Is PSPP More Efficient?

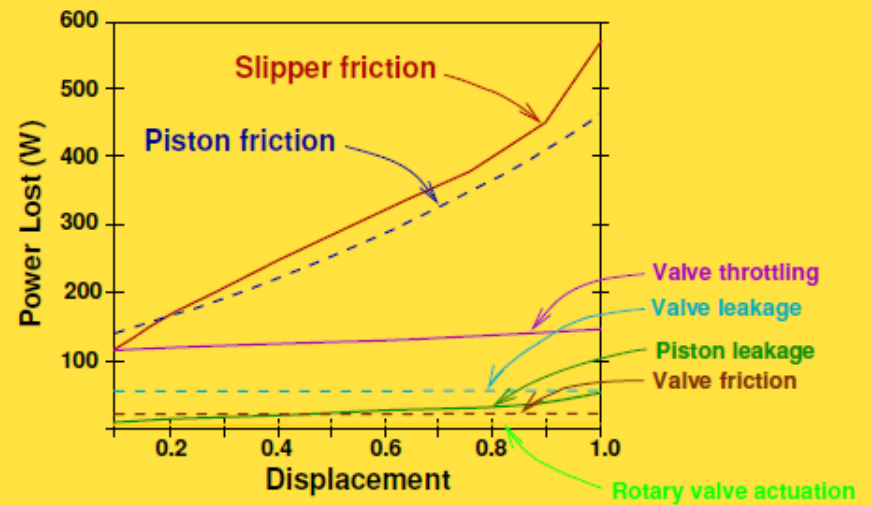
Simulated losses in 48 cc pumps operating at 200 bar and 1800 RPM:

Swashplate pump



The two highest losses are slipper and valve plate friction

PSPP pump



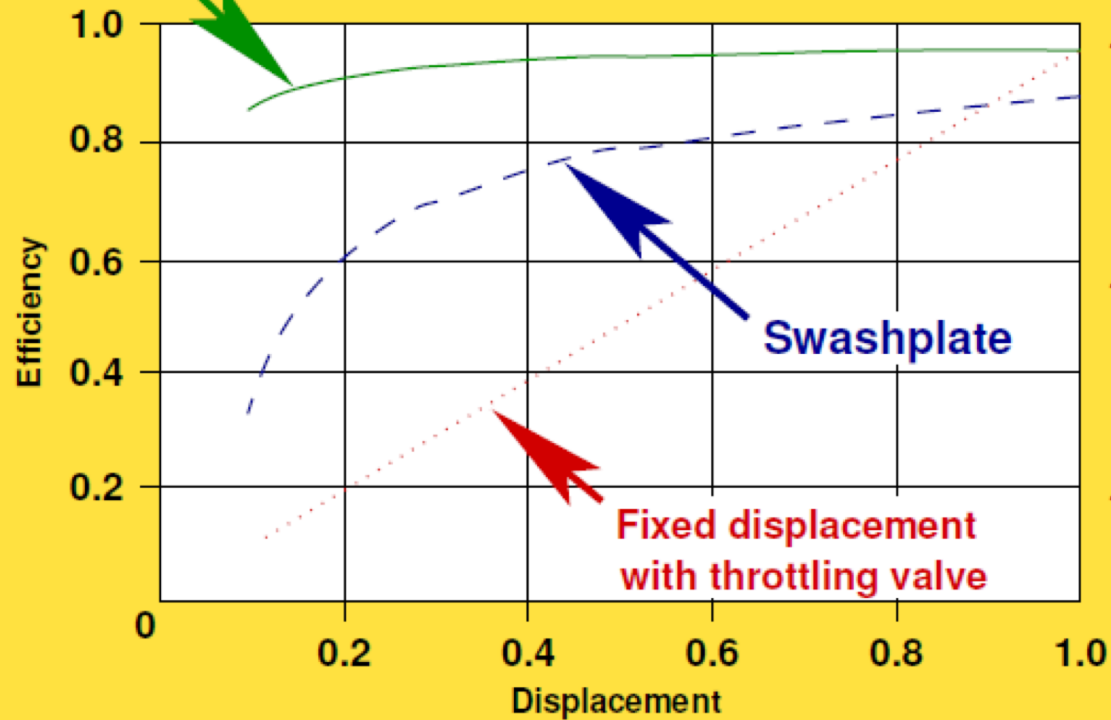
** The valve plate is eliminated*
** Slipper friction scales with displacement*



Technical Payoffs:

PSPP

Approximate Efficiencies
of Different Pump Technologies



+ Saves energy!
(Fluid power accounts for ~3% of all domestic energy usage)

+ Many hydraulic systems are run at partial power most of the time

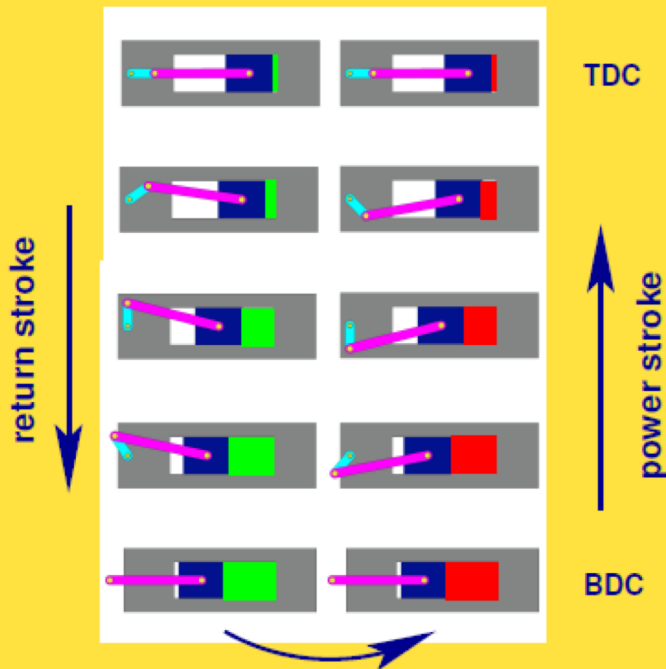
+ Other system components (especially cooling system) can be downsized



What is Partial Stroke Piston Pressurization (PSPP)?

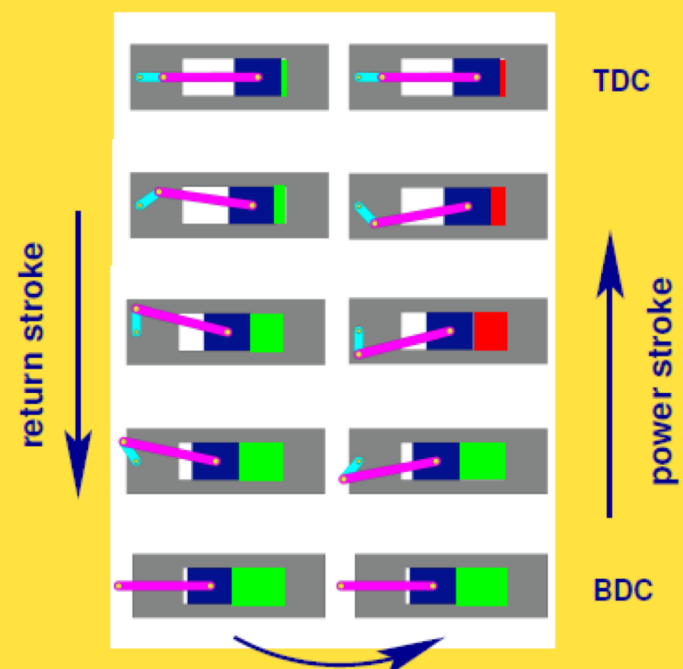
Variable Displacement Swashplate:
Piston is subjected to high pressure for the entire power stroke

 : low pressure  : high pressure

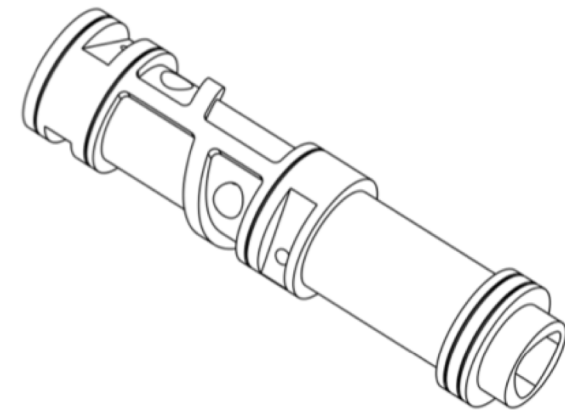
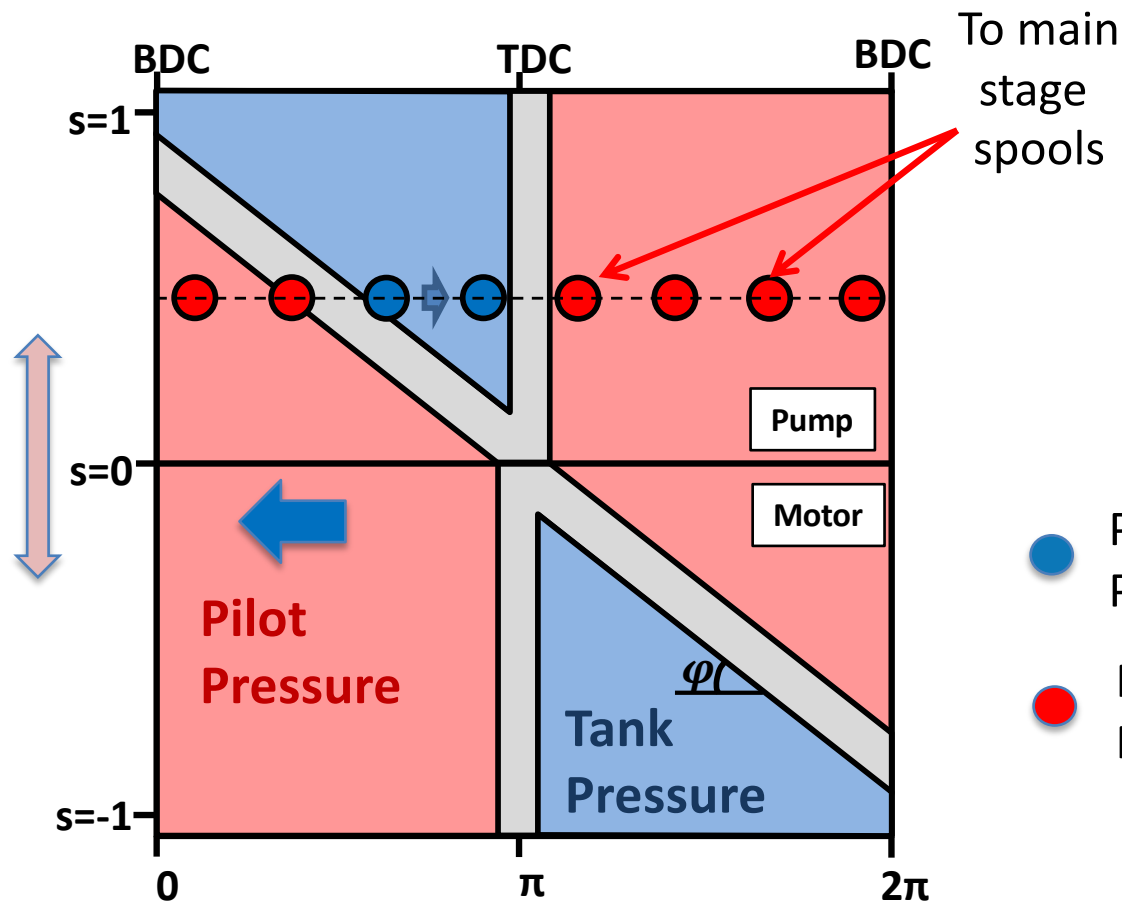


PSPP:
Piston is subjected to high pressure for only a fraction of the power stroke

 : low pressure  : high pressure



Pilot Spool Profile



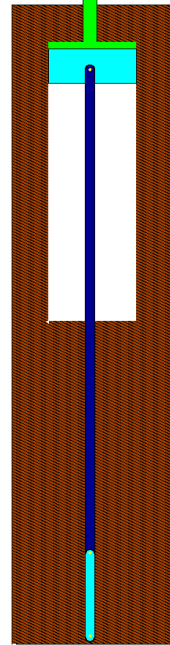
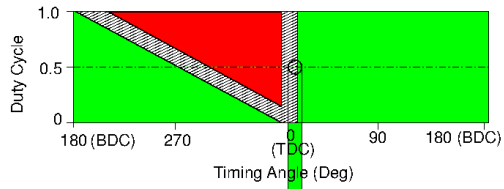
- Pilot = P_{tank} ,
Piston enabled (to high P)
- Pilot = P_{pilot} ,
Piston disabled (to tank)

- Spool translation: changes stroke
 - Pump starts stroke late and motor ends stroke early
 - Ideal for reducing compressibility loss

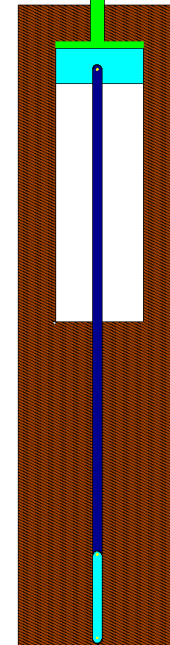
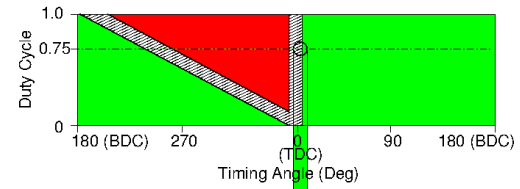




Animation



$S = 0.5$



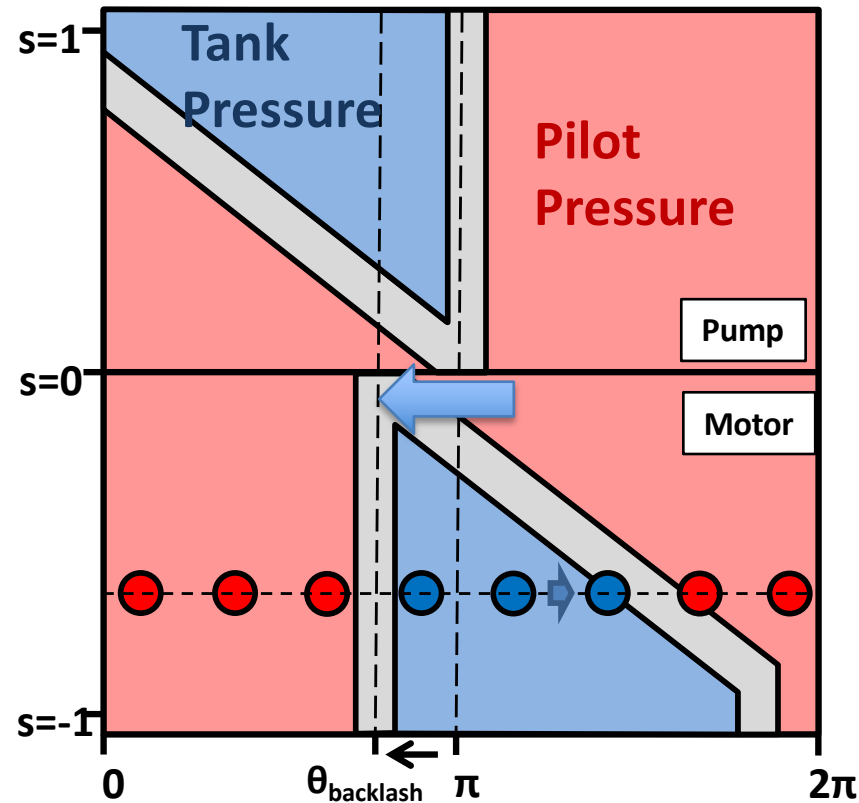
$S = 0.75$

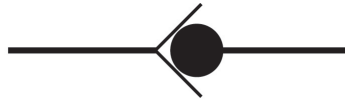




Pre-compression backlash

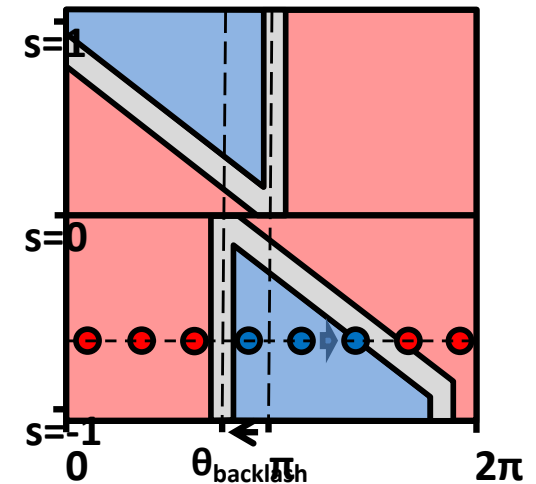
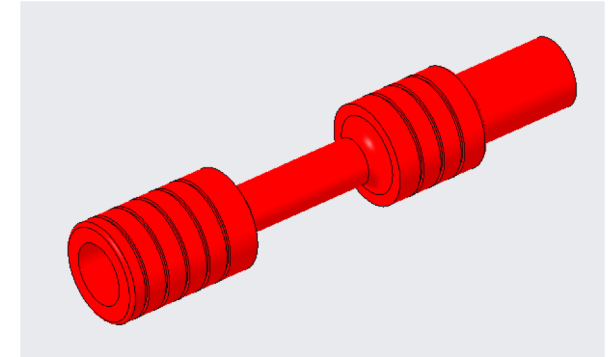
- Shift motor timing so the transition between low and high pressure in the piston chambers precedes TDC position
 - add backlash between shaft and wobble plate





Improvements

- Radial clearance on mainstage valves has been reduced from ~ 40 microns to ~ 4 microns
- Backlash angle setting now accessible from outside of pump case
- New mechanism for manually setting duty cycle of rotary spool



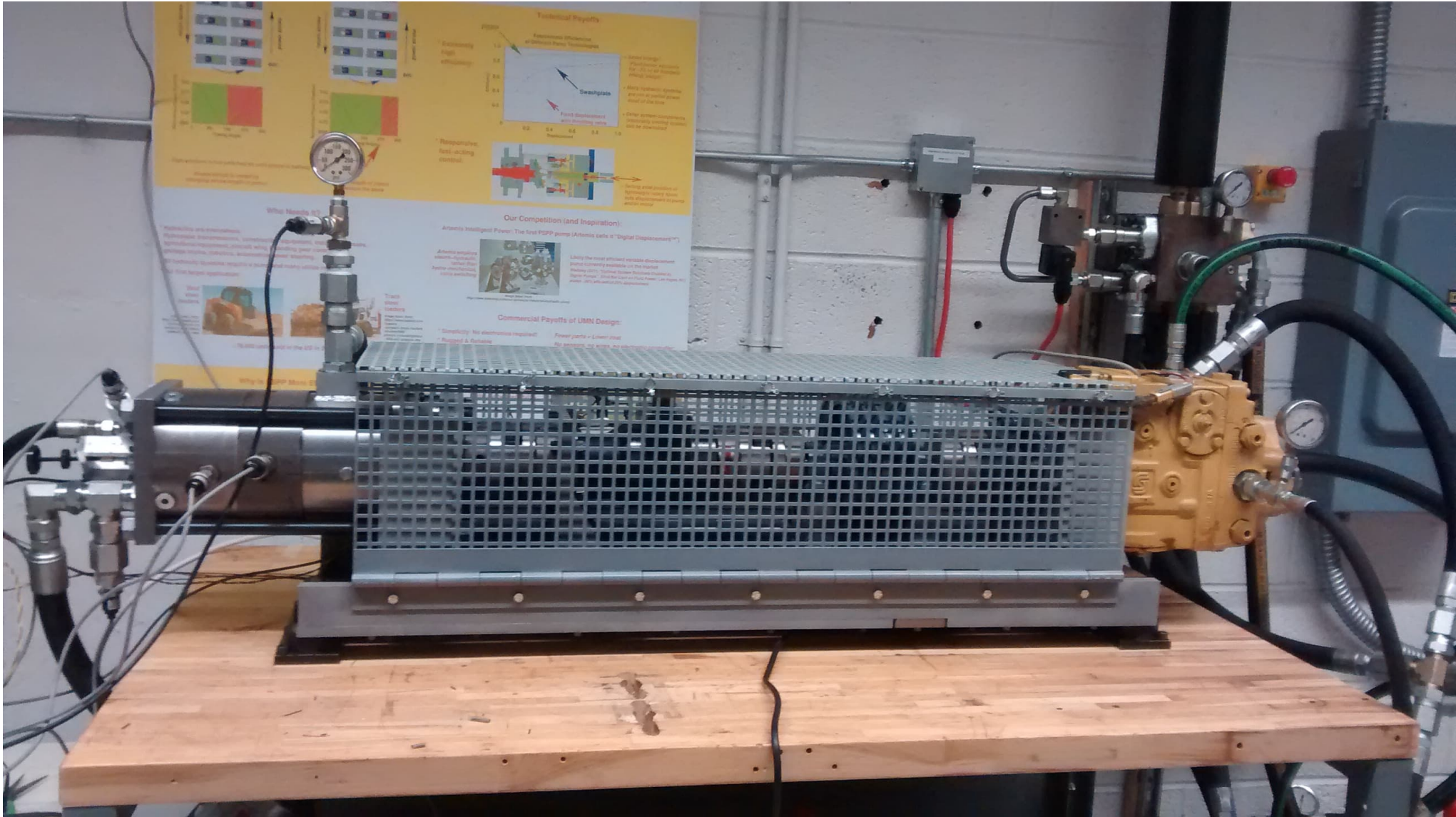


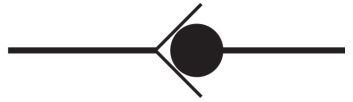
Improvements

- Rebuilt test stand and data acquisition system
- Able to see pumping when run at 1000psi

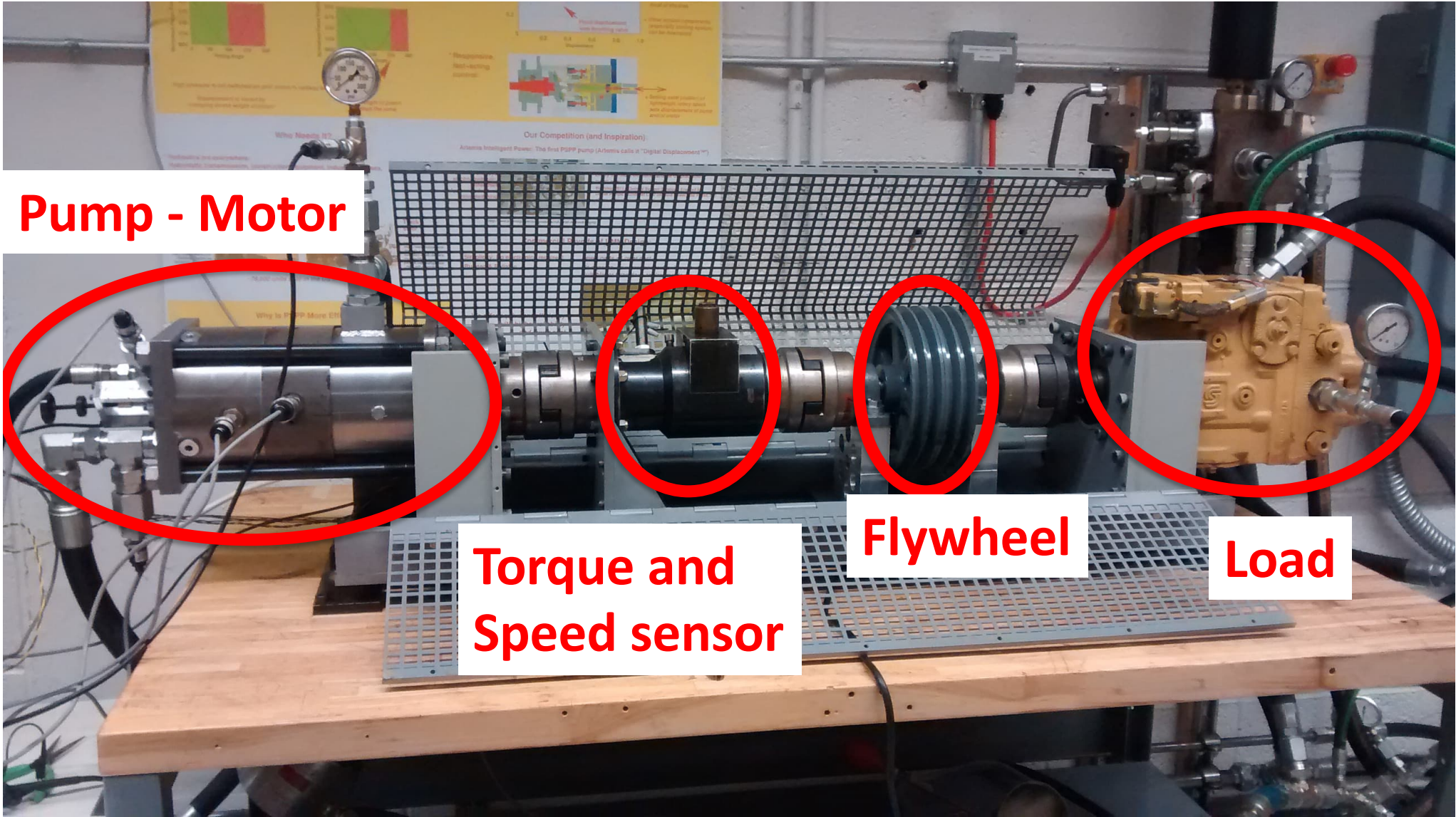


Test Stand





Test Stand



Pump - Motor

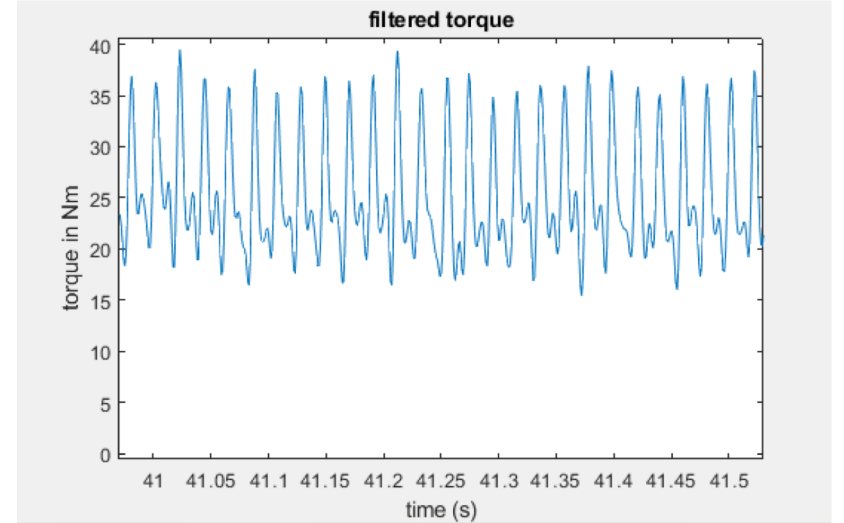
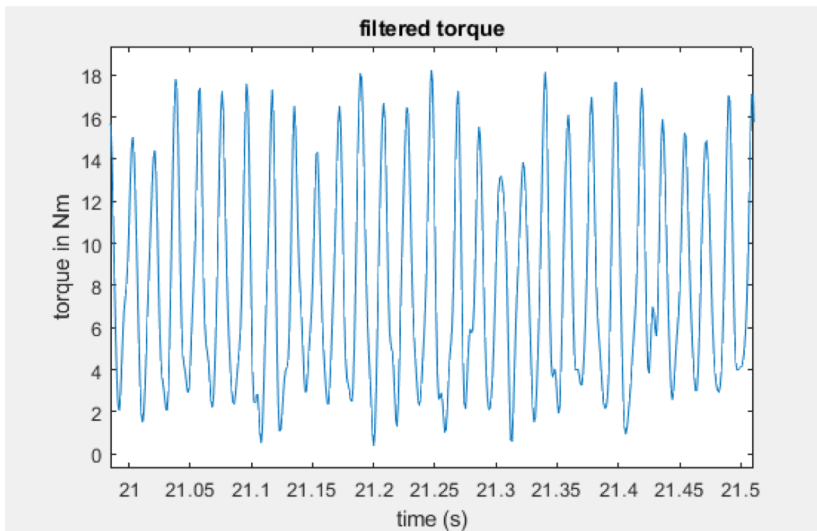
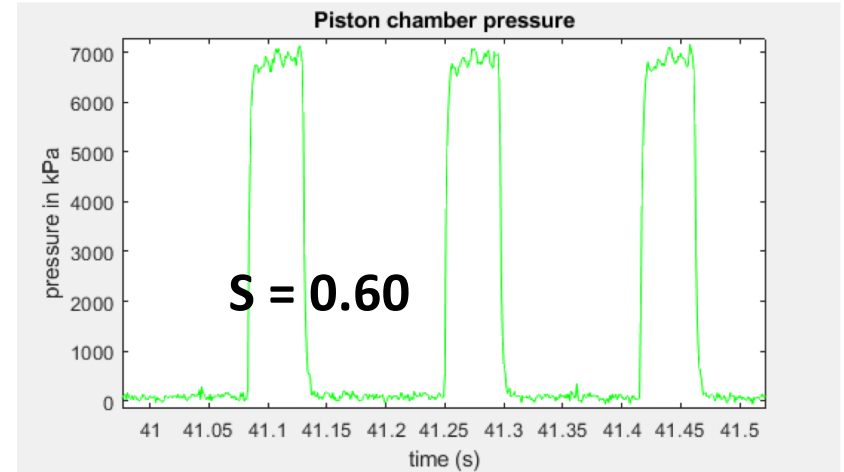
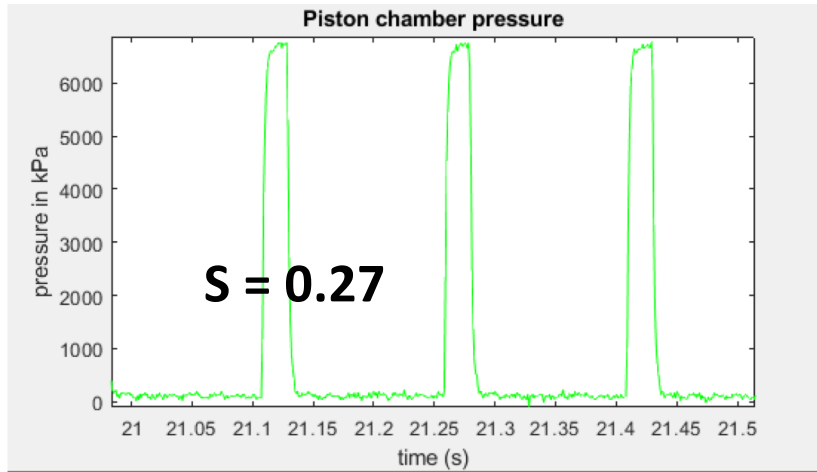
**Torque and
Speed sensor**

Flywheel

Load



Results – pump efficiency data





Results – pump efficiency data

$S = 0.27$, measured efficiency = 6%

$S = 0.60$, measured efficiency = 10%

Potential reasons for low efficiency

- Pilot line leakage (mainstage valves could be moving too slowly causing throttling losses)
- Backlash timing set incorrectly
- Could be run at higher pressure



Conclusions

- Discrete piston control using mechanical valving has advantages of simplicity and ruggedness
- Our design uses:
 - Rotary pilot, 3-way spool main stage, partial stroke
- Measured efficiency is low, but should be improved by removing pilot leakage and setting timing angle

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